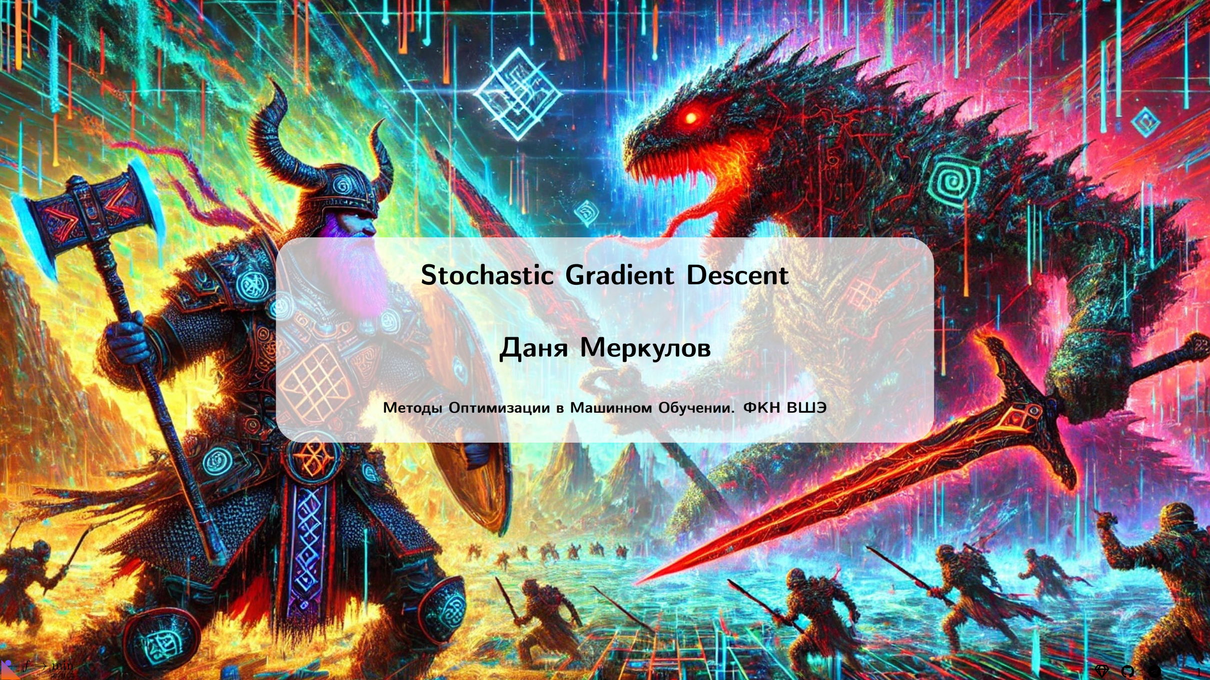

Stochastic Gradient Descent

Даня Меркулов

Методы Оптимизации в Машинном Обучении. ФКН ВШЭ

Finite-sum problem

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We consider classic finite-sample average minimization:

$$\min_{x \in \mathbb{R}^p} f(x) = \min_{x \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^{n} f_i(x)$$

loss на 1 элементе обуч. выборки

The gradient descent acts like follows:

$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^{n} \nabla f_i(x)$$

$$\nabla f(x) = \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x)$$

(GD)

- Convergence with constant α or line search.

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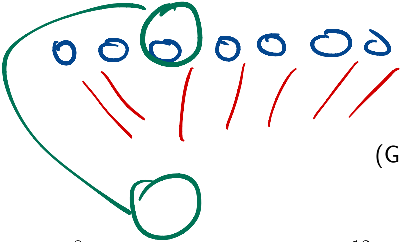

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$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^{n} \nabla f_i(x) \tag{GD}$$

- Convergence with constant α or line search.
- Iteration cost is linear in n. For ImageNet $n \approx 1.4 \cdot 10^7$, for WikiText $n \approx 10^8$. For FineWeb $n \approx 15 \cdot 10^{12}$ tokens.

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Let's switch from the full gradient calculation to its unbiased estimator, when we randomly choose i_k index of point at each iteration uniformly:

$$x_{k+1} = x_k - \alpha_k \nabla f_{i_k}(x_k) \tag{SGD}$$

стохастический градиент

With $p(i_k = i) = \frac{1}{n}$, the stochastic gradient is an unbiased estimate of the gradient, given by:

$$\mathbb{E}[\nabla f_{i_k}(x)] = \sum_{i=1}^{n} p(i_k = i) \nabla f_i(x) = \sum_{i=1}^{n} \frac{1}{n} \nabla f_i(x) = \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x) = \nabla f(x)$$

This indicates that the expected value of the stochastic gradient is equal to the actual gradient of $f(x)$.

Results for Gradient Descent

ε - желаемая точность решения

Stochastic iterations are n times faster, but how many iterations are needed?

If ∇f is Lipschitz continuous then we have:

Assumption	Deterministic Gradient Descent	Stochastic Gradient Descent
PL	$\mathcal{O}\left(\log(1/\varepsilon)\right)$	
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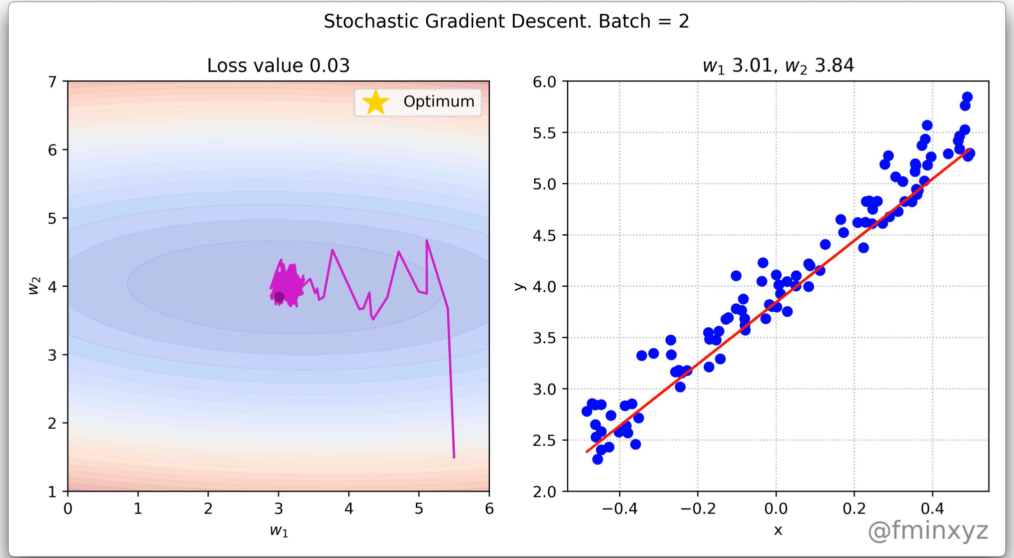
    - Sublinear rate even in strongly-convex case.
    - Bounds are unimprovable under standard assumptions.
    - Oracle returns an unbiased gradient approximation with bounded variance.
- Momentum and Quasi-Newton-like methods do not improve rates in stochastic case. Can only improve constant factors (bottleneck is variance, not condition number).

Stochastic Gradient Descent (SGD)

Typical behaviour



Convergence

Lipschitz continiity implies:

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2}\|x_{k+1} - x_k\|^2$$

Липшицева парабола

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f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2}\|x_{k+1} - x_k\|^2
$$

using (SGD):

$$
x_{k+1} = x_k - \alpha_k \cdot \nabla f_{i_k}(x_k) \longrightarrow x_{k+1} - x_k = -\alpha_k \nabla f_{i_k}(x_k)
$$

$$
f(x_{k+1}) \leq f(x_k) - \alpha_k \langle \nabla f(x_k), \nabla f_{i_k}(x_k) \rangle + \alpha_k^2 \frac{L}{2}\|\nabla f_{i_k}(x_k)\|^2
$$

Чаще всего используется 2 вида оценок

в среднем:

$$
\mathbb{E}\left[f(x_k) - f^*\right] \leq \ldots\ldots
$$

с большой вероятностью:

$$
\mathbb{P}(\text{невязка отклоняется от оценки на} \geq \Delta) \leq \ldots
$$

вероятность больших отклонений

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Now let's take expectation with respect to i_k:

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$$f(x_k) - \alpha_k \langle \nabla f(x_k), \mathbb{E} \nabla f_{i_k}(x_k) \rangle + \frac{\alpha_k^2 L}{2} \mathbb{E}\|\nabla f_{i_k}(x_k)\|^2$$

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Using linearity of expectation:

$= \nabla f(x_k)$

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ХОРОШО

Since uniform sampling implies unbiased estimate of gradient: $\mathbb{E}[\nabla f_{i_k}(x_k)] = \nabla f(x_k)$:

$$\mathbb{E}[f(x_{k+1})] \leq f(x_k) - \alpha_k \|\nabla f(x_k)\|^2 + \alpha_k^2 \frac{L}{2} \mathbb{E}[\|\nabla f_{i_k}(x_k)\|^2] \qquad (1)$$

ПЛОХО

Smooth PL case with constant learning rate

> Пусть f — L-гладкая функция, удовлетворяющая условию Поляка-Лоясиевича (PL) с константой $\mu > 0$, а дисперсия стохастического градиента ограничена: $\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$. Тогда стохастический градиентный спуск с постоянным шагом $\alpha < \frac{1}{2\mu}$ гарантирует
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$$\leq (1 - 2\alpha_k\mu)[f(x_k) - f^*] + \frac{L\sigma^2\alpha_k^2}{2}.$$

Convergence. Smooth PL case.

Пусть f — L-гладкая функция, удовлетворяющая условию Поляка-Лоясиевича (PL) с константой $\mu > 0$, а дисперсия стохастического градиента ограничена: $\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$. Тогда стохастический градиентный спуск с убывающим шагом $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ гарантирует

$$
\mathbb{E}[f(x_k) - f^*] \leq \frac{L\sigma^2}{2\mu^2 k}
$$

1. Consider **decreasing stepsize** strategy with $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ we obtain

Convergence. Smooth PL case.

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1. Consider **decreasing stepsize** strategy with $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ we obtain

$$1-2\alpha_k\mu = \underbrace{\frac{(k+1)^2}{(k+1)^2}}_{1} - \frac{2k+1}{(k+1)^2} = \frac{k^2}{(k+1)^2}$$

Convergence. Smooth PL case.

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$$1 - 2\alpha_k\mu = \frac{(k+1)^2}{(k+1)^2} - \frac{2k+1}{(k+1)^2} = \frac{k^2}{(k+1)^2} \quad \mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{k^2}{(k+1)^2}[f(x_k) - f^*] + \frac{L\sigma^2(2k+1)^2}{8\mu^2(k+1)^4}$$

Convergence. Smooth PL case.

Пусть f — L-гладкая функция, удовлетворяющая условию Поляка-Лоясиевича (PL) с константой $\mu > 0$, а дисперсия стохастического градиента ограничена: $\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$. Тогда стохастический градиентный спуск с убывающим шагом $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ гарантирует

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$$(2k+1)^2 < (2k+2)^2 = 4(k+1)^2 \qquad \leq \frac{k^2}{(k+1)^2}[f(x_k) - f^*] + \frac{L\sigma^2}{2\mu^2(k+1)^2}$$

$\Big| \cdot (k+1)^2$

Convergence. Smooth PL case.

Пусть f — L-гладкая функция, удовлетворяющая условию Поляка-Лоясиевича (PL) с константой $\mu > 0$, а дисперсия стохастического градиента ограничена: $\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$. Тогда стохастический градиентный спуск с убывающим шагом $\alpha_k = \frac{2k+1}{2\mu(k+1)^2}$ гарантирует

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$$\overset{1-2\alpha_k\mu = \frac{(k+1)^2}{(k+1)^2} - \frac{2k+1}{(k+1)^2} = \frac{k^2}{(k+1)^2}}{\quad} \mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{k^2}{(k+1)^2}[f(x_k) - f^*] + \frac{L\sigma^2(2k+1)^2}{8\mu^2(k+1)^4}$$

$$\overset{(2k+1)^2 < (2k+2)^2 = 4(k+1)^2}{\quad} \leq \frac{k^2}{(k+1)^2}[f(x_k) - f^*] + \frac{L\sigma^2}{2\mu^2(k+1)^2}$$

2. Multiplying both sides by $(k+1)^2$ and letting $\delta_f(k) \equiv k^2\mathbb{E}[f(x_k) - f^*]$ we get

$$(k+1)^2\mathbb{E}[f(x_{k+1}) - f^*] \leq k^2\mathbb{E}[f(x_k) - f^*] + \frac{L\sigma^2}{2\mu^2}$$

$$\delta_f(k+1) \leq \delta_f(k) + \frac{L\sigma^2}{2\mu^2}.$$

Convergence. Smooth PL case.

3. Summing up previous inequality from $i = 0$ to k and using the fact that $\delta_f(0) = 0$ we get

which gives the stated rate.

Convergence. Smooth PL case.

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Convergence. Smooth PL case.

3. Summing up previous inequality from $i = 0$ to k and using the fact that $\delta_f(0) = 0$ we get

$$\delta_f(i+1) \leq \delta_f(i) + \frac{L\sigma^2}{2\mu^2}$$

$$\sum_{i=0}^{k} \left[\delta_f(i+1) - \delta_f(i)\right] \leq \sum_{i=0}^{k} \frac{L\sigma^2}{2\mu^2}$$

which gives the stated rate.

Convergence. Smooth PL case.

3. Summing up previous inequality from $i = 0$ to k and using the fact that $\delta_f(0) = 0$ we get

$$
\begin{aligned}
\delta_f(i+1) &\leq \delta_f(i) + \frac{L\sigma^2}{2\mu^2} \\
\sum_{i=0}^{k} \left[\delta_f(i+1) - \delta_f(i) \right] &\leq \sum_{i=0}^{k} \frac{L\sigma^2}{2\mu^2} \\
\delta_f(k+1) - \delta_f(0) &\leq \frac{L\sigma^2 (k+1)}{2\mu^2}
\end{aligned}
$$

$\delta_f(0) = \sigma^2 \cdot \mathbb{E}[f(x) - f^*] = 0$

which gives the stated rate.

Convergence. Smooth PL case.

3. Summing up previous inequality from $i = 0$ to k and using the fact that $\delta_f(0) = 0$ we get

$$
\begin{aligned}
\delta_f(i+1) &\leq \delta_f(i) + \frac{L\sigma^2}{2\mu^2} \\
\sum_{i=0}^{k} \left[\delta_f(i+1) - \delta_f(i)\right] &\leq \sum_{i=0}^{k} \frac{L\sigma^2}{2\mu^2} \\
\delta_f(k+1) - \delta_f(0) &\leq \frac{L\sigma^2 (k+1)}{2\mu^2} \\
(k+1)^2 \mathbb{E}[f(x_{k+1}) - f^*] &\leq \frac{L\sigma^2 (k+1)}{2\mu^2}
\end{aligned}
$$

$| : (k+1)^2$

$\mathbb{E}\left[f(x_{k+1}) - f^*\right] \leq \frac{L\sigma^2}{2\mu^2(k+1)}$

which gives the stated rate.

Convergence. Smooth PL case.

3. Summing up previous inequality from $i = 0$ to k and using the fact that $\delta_f(0) = 0$ we get

$$\delta_f(i+1) \leq \delta_f(i) + \frac{L\sigma^2}{2\mu^2}$$

$$\sum_{i=0}^{k} \left[\delta_f(i+1) - \delta_f(i)\right] \leq \sum_{i=0}^{k} \frac{L\sigma^2}{2\mu^2}$$

$$\delta_f(k+1) - \delta_f(0) \leq \frac{L\sigma^2(k+1)}{2\mu^2}$$

$$(k+1)^2 \mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{L\sigma^2(k+1)}{2\mu^2}$$

$$\mathbb{E}[f(x_k) - f^*] \leq \frac{L\sigma^2}{2\mu^2 k}$$

сублинейная

$\sim \frac{1}{k}$

which gives the stated rate.

Convergence. Smooth convex case (bounded variance)

Auxiliary notation

For a (possibly) non-constant stepsize sequence $(\alpha_t)_{t\geq 0}$ define the stepsize-weighted average

$$\bar{x}_k \stackrel{\text{def}}{=} \frac{1}{\sum_{t=0}^{k-1} \alpha_t} \sum_{t=0}^{k-1} \alpha_t \, x_t \,, \qquad k \geq 1.$$

Everywhere below $f^* \equiv \min_x f(x)$ and $x^* \in \arg\min_x f(x)$.

Smooth convex case with constant learning rate

Пусть f — выпуклая функция (не обязательно гладкая), а дисперсия стохастического градиента ограничена $\mathbb{E}\left[\|\nabla f_{i_k}(x_k)\|^2\right] \leq \sigma^2 \quad \forall k$. Если SGD использует постоянный шаг $\alpha_t \equiv \alpha > 0$, то для любого $k \geq 1$

$$\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{\|x_0 - x^*\|^2}{2\alpha\, k} + \frac{\alpha\, \sigma^2}{2}$$

расходится с постоянным шагом

где $\bar{x}_k = \frac{1}{k}\sum_{t=0}^{k-1} x_t$.

При выборе постоянного $\alpha = \frac{\|x_0 - x^*\|}{\sigma\sqrt{k}}$ (зависящего от k) имеем

$$\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{\|x_0 - x^*\|\sigma}{\sqrt{k}} = \mathcal{O}\left(\frac{1}{\sqrt{k}}\right).$$

$\sim \frac{1}{\sqrt{k}}$

Smooth convex case with constant learning rate

1. Начнём с разложения квадрата расстояния до минимума:

$$\|x_{k+1} - x^*\|^2 = \|x_k - \alpha \nabla f_{i_k}(x_k) - x^*\|^2 = \|x_k - x^*\|^2 - 2\alpha \langle \nabla f_{i_k}(x_k), x_k - x^* \rangle + \alpha^2 \|\nabla f_{i_k}(x_k)\|^2.$$

Smooth convex case with constant learning rate

1. Начнём с разложения квадрата расстояния до минимума:

$$\|x_{k+1} - x^*\|^2 = \|x_k - \alpha \nabla f_{i_k}(x_k) - x^*\|^2 = \|x_k - x^*\|^2 - 2\alpha\langle \nabla f_{i_k}(x_k), x_k - x^*\rangle + \alpha^2 \|\nabla f_{i_k}(x_k)\|^2.$$

2. Берём условное матожидание по i_k (обозначим $\mathbb{E}_k[\cdot] = \mathbb{E}[\cdot|x_k]$), используем свойство $\mathbb{E}_k[\nabla f_{i_k}(x_k)] = \nabla f(x_k)$, ограниченность дисперсии $\mathbb{E}_k[\|\nabla f_{i_k}(x_k)\|^2] \leq \sigma^2$ и выпуклость f (которая даёт $\langle \nabla f(x_k), x_k - x^*\rangle \geq f(x_k) - f^*$):

$$\begin{aligned}\mathbb{E}_k[\|x_{k+1} - x^*\|^2] &= \|x_k - x^*\|^2 - 2\alpha\langle \nabla f(x_k), x_k - x^*\rangle + \alpha^2 \mathbb{E}_k[\|\nabla f_{i_k}(x_k)\|^2] \\ &\leq \|x_k - x^*\|^2 - 2\alpha(f(x_k) - f^*) + \alpha^2\sigma^2.\end{aligned}$$

$$f^* \geq f(x_k) + \langle \nabla f(x_k), x^* - x_k\rangle$$

$$-\langle \nabla f(x_k), x_k - x^*\rangle \leq f^* - f(x_k) \leq -(f(x_k) - f^*)$$

Smooth convex case with constant learning rate

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$$\begin{aligned}\mathbb{E}_k[\|x_{k+1} - x^*\|^2] &= \|x_k - x^*\|^2 - 2\alpha \langle \nabla f(x_k), x_k - x^* \rangle + \alpha^2 \mathbb{E}_k[\|\nabla f_{i_k}(x_k)\|^2] \\ &\leq \|x_k - x^*\|^2 - 2\alpha \big(f(x_k) - f^*\big) + \alpha^2 \sigma^2.\end{aligned}$$

3. Переносим член с $f(x_k)$ влево и берём полное матожидание:

$$2\alpha \mathbb{E}[f(x_k) - f^*] \leq \mathbb{E}[\|x_k - x^*\|^2] - \mathbb{E}[\|x_{k+1} - x^*\|^2] + \alpha^2 \sigma^2.$$

Smooth convex case with constant learning rate

1. Начнём с разложения квадрата расстояния до минимума:

$$
\|x_{k+1} - x^*\|^2 = \|x_k - \alpha \nabla f_{i_k}(x_k) - x^*\|^2 = \|x_k - x^*\|^2 - 2\alpha \langle \nabla f_{i_k}(x_k), x_k - x^* \rangle + \alpha^2 \|\nabla f_{i_k}(x_k)\|^2.
$$

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$$
\begin{aligned}
\mathbb{E}_k[\|x_{k+1} - x^*\|^2] &= \|x_k - x^*\|^2 - 2\alpha \langle \nabla f(x_k), x_k - x^* \rangle + \alpha^2 \mathbb{E}_k[\|\nabla f_{i_k}(x_k)\|^2] \\
&\leq \|x_k - x^*\|^2 - 2\alpha \big(f(x_k) - f^*\big) + \alpha^2 \sigma^2.
\end{aligned}
$$

3. Переносим член с $f(x_k)$ влево и берём полное матожидание:

$$
2\alpha \mathbb{E}[f(x_k) - f^*] \leq \mathbb{E}[\|x_k - x^*\|^2] - \mathbb{E}[\|x_{k+1} - x^*\|^2] + \alpha^2 \sigma^2.
$$

4. Суммируем (телескопируем) по $t = 0, \ldots, k-1$:

$$
\begin{aligned}
\sum_{t=0}^{k-1} 2\alpha\, \mathbb{E}[f(x_t) - f^*] &\leq \sum_{t=0}^{k-1} \left(\mathbb{E}[\|x_t - x^*\|^2] - \mathbb{E}[\|x_{t+1} - x^*\|^2] \right) + \sum_{t=0}^{k-1} \alpha^2 \sigma^2 \\
&= \mathbb{E}[\|x_0 - x^*\|^2] - \mathbb{E}[\|x_k - x^*\|^2] + k\, \alpha^2 \sigma^2 \\
&\leq \|x_0 - x^*\|^2 + k\, \alpha^2 \sigma^2.
\end{aligned}
$$

Smooth convex case with constant learning rate

5. Делим на $2\alpha k$:

$$
\frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t) - f^*] \leq \frac{\|x_0 - x^*\|^2}{2\alpha k} + \frac{\alpha\sigma^2}{2}.
$$

Smooth convex case with constant learning rate

5. Делим на $2\alpha k$:

$$\frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t) - f^*] \leq \frac{\|x_0 - x^*\|^2}{2\alpha k} + \frac{\alpha\sigma^2}{2}.$$

6. Используя выпуклость f и неравенство Йенсена для усреднённой точки $\bar{x}_k = \frac{1}{k}\sum_{t=0}^{k-1} x_t$:

$$\mathbb{E}[f(\bar{x}_k)] \leq \mathbb{E}\left[\frac{1}{k}\sum_{t=0}^{k-1} f(x_t)\right] = \frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t)].$$

Вычитая f^* из обеих частей, получаем:

$$\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t) - f^*].$$

$$\leq \frac{R^2}{2\alpha k} + \frac{\alpha\sigma^2}{2}$$

Smooth convex case with constant learning rate

5. Делим на $2\alpha k$:

$$\frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t) - f^*] \leq \frac{\|x_0 - x^*\|^2}{2\alpha k} + \frac{\alpha\sigma^2}{2}.$$

6. Используя выпуклость f и неравенство Йенсена для усреднённой точки $\bar{x}_k = \frac{1}{k}\sum_{t=0}^{k-1} x_t$:

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Вычитая f^* из обеих частей, получаем:

$$\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{1}{k}\sum_{t=0}^{k-1}\mathbb{E}[f(x_t) - f^*].$$

7. Объединяя (5) и (6), получаем искомую оценку:

$$\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{\|x_0 - x^*\|^2}{2\alpha\, k} + \frac{\alpha\,\sigma^2}{2}.$$

Smooth convex case with decreasing learning rate

$$\alpha_k = \frac{\alpha_0}{\sqrt{k+1}}, \quad 0 < \alpha_0 \leq \frac{1}{4L}$$

При тех же предположениях, но со спадом шага $\alpha_k = \frac{\alpha_0}{\sqrt{k+1}}$

$$\boxed{\mathbb{E}[f(\bar{x}_k) - f^*] \leq \frac{5\|x_0 - x^*\|^2}{4\alpha_0\sqrt{k}} + 5\alpha_0\sigma^2 \frac{\log(k+1)}{\sqrt{k}}} = \mathcal{O}\left(\frac{\log k}{\sqrt{k}}\right).$$

Mini-batch SGD

Mini-batch SGD

Approach 1: Control the sample size

The deterministic method uses all n gradients:

$$\nabla f(x_k) = \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x_k).$$

The stochastic method approximates this using just 1 sample:

стох. градиент

$$\nabla f_{ik}(x_k) \approx \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x_k).$$

честный градиент

A common variant is to use a larger sample B_k ("mini-batch"):

$$\frac{1}{|B_k|} \sum_{i \in B_k} \nabla f_i(x_k) \approx \frac{1}{n} \sum_{i=1}^{n} \nabla f_i(x_k),$$

particularly useful for vectorization and parallelization.
For example, with 16 cores set $|B_k| = 16$ and compute 16 gradients at once.

Mini-Batching as Gradient Descent with Error

The SG method with a sample B_k ("mini-batch") uses iterations:

$$x_{k+1} = x_k - \alpha_k \left(\frac{1}{|B_k|} \sum_{i \in B_k} \nabla f_i(x_k) \right).$$

Let's view this as a "gradient method with error":

$$x_{k+1} = x_k - \alpha_k (\nabla f(x_k) + e_k),$$

where e_k is the difference between the approximate and true gradient.

If you use $\alpha_k = \frac{1}{L}$, then using the descent lemma, this algorithm has:

$$f(x_{k+1}) \leq f(x_k) - \frac{1}{2L} \|\nabla f(x_k)\|^2 + \frac{1}{2L} \|e_k\|^2,$$

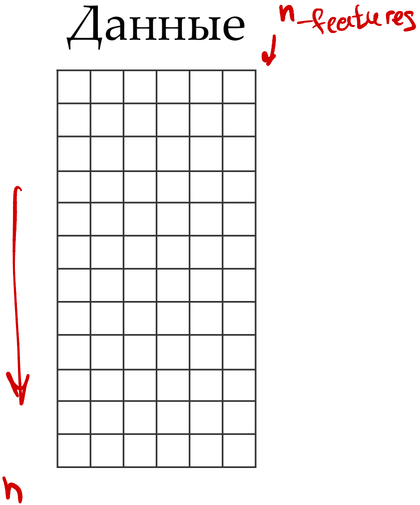
for any error e_k.

Effect of Error on Convergence Rate

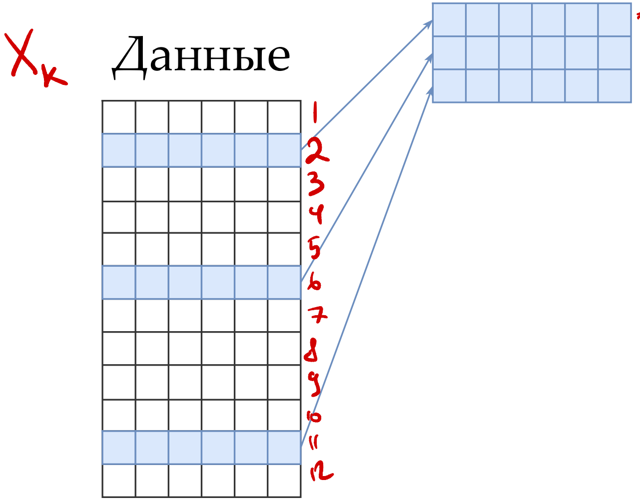
Our progress bound with $\alpha_k = \frac{1}{L}$ and error in the gradient of e_k is:

$$f(x_{k+1}) \leq f(x_k) - \frac{1}{2L}\|\nabla f(x_k)\|^2 + \frac{1}{2L}\|e_k\|^2.$$

Идея SGD и батчей



Идея SGD и батчей



$f_2(x_k)$, $\nabla f_2(x_k)$

$f_6(x_k)$, $\nabla f_6(x_k)$

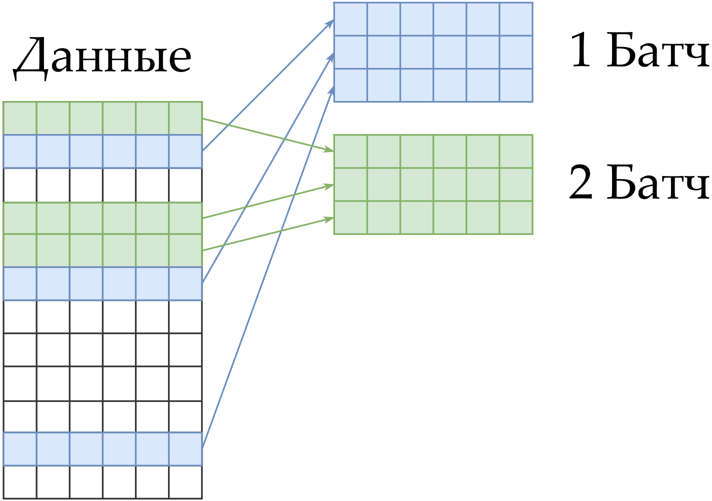
$f_{12}(x_k)$, $\nabla f_{12}(x_k)$

стох. градиент

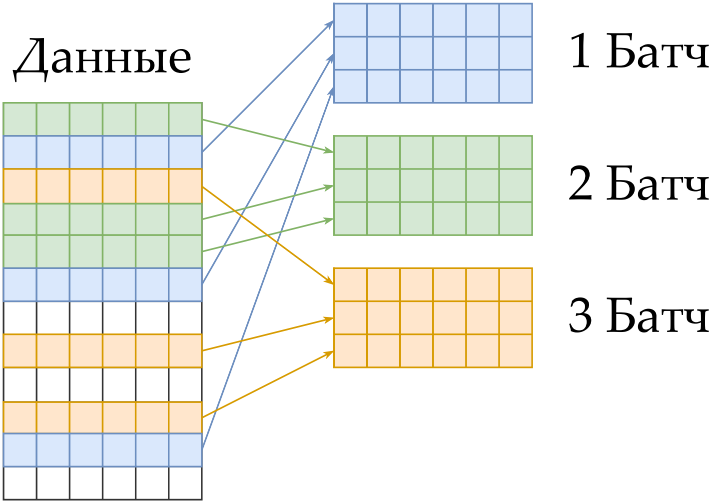
$$g_k = \frac{1}{3}\left(\nabla f_2(x_k) + \nabla f_6(x_k) + \nabla f_{12}(x_k)\right)$$

$$x_{k+1} = x_k - \alpha_k g_k$$

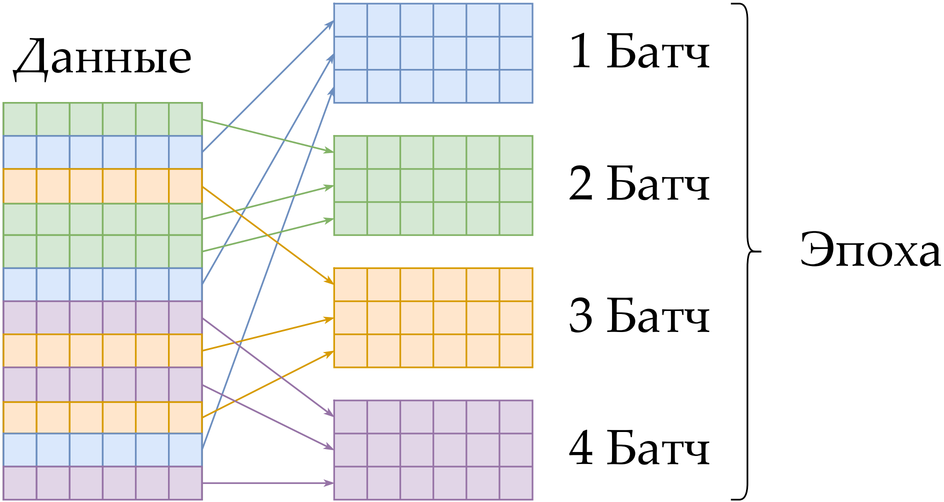
Идея SGD и батчей



Идея SGD и батчей

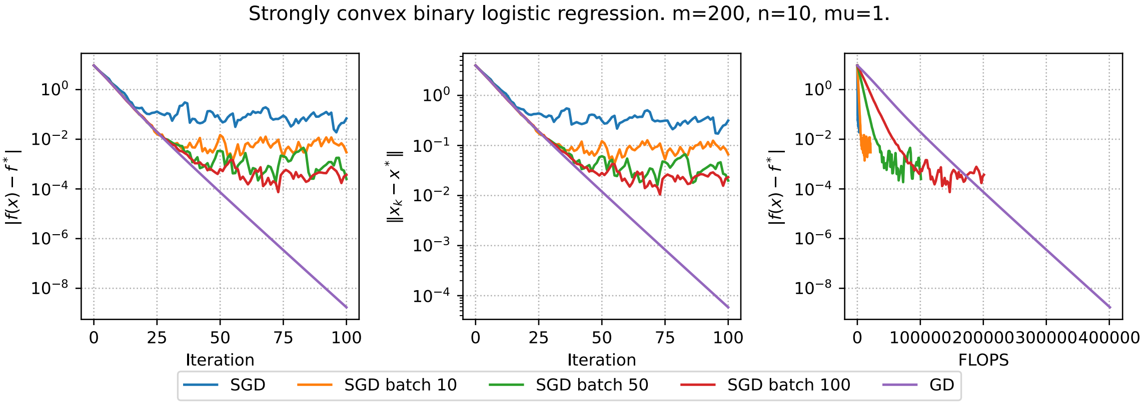


Идея SGD и батчей



Main problem of SGD

$$f(x) = \frac{\mu}{2}\|x\|_2^2 + \frac{1}{m}\sum_{i=1}^m \log(1 + \exp(-y_i\langle a_i, x\rangle)) \to \min_{x \in \mathbb{R}^n}$$



Основные результаты сходимости SGD

Пусть f - L-гладкая μ-сильно выпуклая функция, а дисперсия стохастического градиента конечна ($\mathbb{E}[\|\nabla f_i(x_k)\|^2] \leq \sigma^2$). Тогда траектория стохастического градиентного спуска с постоянным шагом $\alpha < \frac{1}{2\mu}$ будет гарантировать:

$$\mathbb{E}[f(x_{k+1}) - f^*] \leq (1 - 2\alpha\mu)^k [f(x_0) - f^*] + \frac{L\sigma^2\alpha}{4\mu}.$$

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$$\mathbb{E}[f(x_{k+1}) - f^*] \leq \frac{L\sigma^2}{2\mu^2(k+1)}$$

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- Two-phase Newton-like method achieves $\mathcal{O}\left(\frac{1}{k}\right)$ without strong convexity.